

overview

- about program correctness
- propositional dynamic logic

advanced logic
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lecture 11

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program correctness

correctness specification:

formal description about how a program is supposed to behave

program is correct:

its executions satisfy the specification

partial and total correctness

partial correctness:

if the program starts satisfying ϕ ,
and if it halts,
then when it halts ψ is satisfied

total correctness:

it is partially correct,
and it terminates whenever started satisfying ϕ

recall: program for gcd

```
while  $y \neq 0$  do  
  begin  
     $z := x \bmod y;$   
     $x := y;$   
     $y := z;$   
  end  
return  $x$ 
```

approach to program correctness

we restrict attention to input-output behaviour

specification consists of

input condition ϕ and output condition ψ

correctness for gcd

if the input variables x and y are c and d
the output value of x is the gcd of c and d
and the program halts

while programs

atomic instruction: assignment

$x := t$ with x a variable and t a term

sequential composition

$\alpha; \beta$

conditional

if ϕ then α else β

iteration: while

while ϕ do α

illustration

the gcd program is while σ do α with σ is $y \neq 0$

precondition ϕ is $\neg(x = 0 \wedge y = 0) \wedge x = c \wedge y = d$

postcondition ψ is $x = \text{gcd}(c, d)$

invariant I is $\neg(x = 0 \wedge y = 0) \wedge \text{gcd}(x, y) = \text{gcd}(c, d)$

we have $\phi \rightarrow I$

we have $I \wedge \neg\sigma \rightarrow \psi$

rules for Hoare logic

one rule for every program construct, for example for while:

$$\frac{\{\phi \wedge \sigma\} \alpha \{\phi\}}{\{\phi\} \text{while } \sigma \text{ do } \alpha \{\phi \wedge \neg\sigma\}}$$

and a weakening rule:

$$\frac{\phi \rightarrow \phi' \quad \{\phi'\} \alpha \{\psi'\} \quad \psi' \rightarrow \psi}{\{\phi\} \alpha \{\psi\}}$$

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about propositional dynamic logic (PDL)

PDL is a formal system for reasoning about programs:

proving that a program meets its specification, comparing expressive power,
...

PDL is modal so dynamic, so suitable to model computation

PDL interprets programs as input-output relation
(abstracts away from program execution details)

more or less: programs are supposed to halt

program constructors such as composition are interpreted as operations on
input-output relations

ingredients of PDL

multi-modal logic

regular programs

mixed ingredients $[\alpha]\phi$, $\langle\alpha\rangle\phi$, $?\phi$

propositional dynamic logic (PDL): starting point

for every program α we have a modality $\langle\alpha\rangle$

$\langle\alpha\rangle\phi$ intuitively means

it is possible to execute α starting in the current state,
and halt (successfully) in a state satisfying ϕ

$[\alpha]\phi$ intuitively means

for all executions of α :
if α halts (successfully), then it halts in a state satisfying ϕ

set Prog of PDL or regular programs: definition

atomic program

a from a set A of atomic programs

sequential composition

$\alpha; \beta$

non-deterministic choice

$\alpha \cup \beta$

iteration

α^*

test

$\phi?$ with ϕ a formula, so depends on the grammar for formulas

PDL programs: intuitive meaning

a

atomic, indecomposable, step

$\phi?$

if ϕ then skip else abort, that is,

if ϕ holds then continue without changing state,

if ϕ does not hold then block without halting

$\alpha; \beta$

do α , then do β

$\alpha \cup \beta$

nondeterministically choose α or β and execute it

α^*

nondeterministically choose $n \geq 0$ and execute α n times

PDL formulas: definition

atomic formula

p from a set *Var of atomic propositions*

true and false

\top and \perp

negation

$\neg\phi$

conjunction

$\phi \wedge \psi$

diamond

$\langle \alpha \rangle \phi$, with α a *program*, so depends on the grammar for programs

non-determinism

we have non-determinism due to choice \cup

we have non-determinism due to iteration α^*

a trace may not be uniquely determined by its start state

nondeterminism is useful to model situations where we may know the range of possibilities

often a deterministic choice is forced for example for if-then-else

PDL formulas: examples

$[\alpha \cup \beta]\phi$

always if we execute α or β we arrive at a state where ϕ holds

$\langle (\alpha\beta)^* \rangle \phi$

there is a sequence of alternating executions of α and β bringing us to a state where ϕ holds

$\langle \alpha^* \rangle \phi \leftrightarrow \phi \vee \langle \alpha; \alpha^* \rangle \phi$

ϕ holds after a finite number ($n \geq 0$) of α steps

if and only if

either ϕ holds here ($n = 0$), or ($n > 0$) we can do an α step and then more α steps to reach a state where ϕ holds

PDL formulas: more examples

$[\alpha](\phi \wedge \psi) \leftrightarrow [\alpha]\phi \wedge [\alpha]\psi$ (seems a tautology)

$[\alpha; \beta]\phi \leftrightarrow [\alpha][\beta]\phi$ (seems a tautology)

$[\alpha]p \leftrightarrow [\beta]p$ (gives an equivalence between α and β)

towards a semantics for PDL formulas

we obtain the semantics as an instance of multi-modal logic

in particular:

$\mathcal{M}, s \models \langle \alpha \rangle \phi$ iff there is s' such that $(s, s') \in R_\alpha$ and $\mathcal{M}, s' \models \phi$

however:

an arbitrary model does not respect the intended meaning of the programs

therefore we will impose conditions on the relations R_α

mutual dependency: examples

$[p?]p$

if $p?$ halts then in a state satisfying p with p an atomic proposition

$\langle p? \rangle p$

it is possible to execute $p?$ and halt in a state where p holds

$[\alpha]\perp$

α never terminates

$[\alpha]\top$

is always true

$\top?$

is skip

$\perp?$

is fail (? unsuccessful halt)

example

$W = \{u, v, w\}$

$R_a = \{(u, v), (u, w), (v, w), (w, v)\}$

$V(p) = \{u, v\}$

we have $u \models \langle a \rangle \neg p \wedge \langle a \rangle p$

we have $v \models [a] \neg p$

we have $w \models [a] p$

in every world (state) we have $\langle a^* \rangle [(aa)^*] p \wedge \langle a^* \rangle [(aa)^*] \neg p$

example

$$W = \{s, t, u, v\}$$

$$R_a = \{(t, v), (v, t), (s, u), (u, s)\}$$

$$R_b = \{(u, v), (v, u), (s, t), (t, s)\}$$

$$V(p) = \{u, v\}$$

$$V(q) = \{t, v\}$$

we have $p \leftrightarrow [(ab^*a)^*]p$

we have $q \leftrightarrow [(ba^*b)^*]q$

PDL frame: definition

a Prog-frame $\mathcal{F} = (W, \{R_\alpha \mid \alpha \in \text{Prog}\})$ is a PDL-frame if

$$R_{\alpha\beta} = R_\alpha; R_\beta, \text{ and}$$

$$R_{\alpha \cup \beta} = R_\alpha \cup R_\beta, \text{ and}$$

$$R_{\alpha^*} = (R_\alpha)^*$$

so if we know all R_a then we know enough!

what are the definitions on the relations?

intuitive requirements for a PDL model

consider $a; b$ and $R_{a;b}$

consider $a \cup b$ and $R_{a \cup b}$

consider a^* and R_{a^*}

this suggests to start from all the R_a with $a \in A$ an atomic program

but what to do with R_ϕ ? ?

definitions on relations

the **composition** of R and S : $R; S = \{(x, z) \mid \exists y : Rxy \wedge Syz\}$

the **union** of R and S : $R \cup S = \{(x, y) \mid Rxy \vee Sxy\}$

the **identity relation**: $\text{Id} = \{(x, x)\}$

the **n -fold composition** of R : $R^0 = \text{Id}$ and $R^{n+1} = R^n; R$

the **reflexive-transitive closure** of R : $R^* = \bigcup_{n \geq 0} R^n$

note: if xR^*y , then there exists $n \geq 0$ and there exist x_1, \dots, x_{n-1} such that $x = x_0 R x_1 R \dots R x_n = y$

note: R^* is the smallest reflexive and transitive relation containing R

PDL model: definition

a model $\mathcal{M} = (W, \{R_\alpha \mid \alpha \in \text{Prog}\}, V)$ is a PDL-model if

$(W, \{R_\alpha \mid \alpha \in \text{Prog}\})$ is a PDL-frame, and

$$R_{\phi?} = \{(w, w) \mid \mathcal{M}, w \models \phi\}$$

PDL extension: definition

we can get a PDL model as the extension of a model over labels A

Let $\mathcal{M} = (W, \{R_a \mid a \in A\}, V)$ be an A -model

Its **PDL-extension** is defined as $\hat{\mathcal{M}} = (W, \{\hat{R}_\alpha \mid \alpha \in \text{Prog}\}, V)$ with

$$\hat{R}_a = R_a$$

$$\hat{R}_{\alpha;\beta} = \hat{R}_\alpha; \hat{R}_\beta$$

$$\hat{R}_{\alpha \cup \beta} = \hat{R}_\alpha \cup \hat{R}_\beta$$

$$\hat{R}_{\alpha^*} = (R_\alpha)^*$$

$$\hat{R}_{\phi?} = \{(x, x) \mid \mathcal{M}, x \models \phi\}$$